

# Vectors in Three Dimensions

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Fall 2025

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# Three-Dimensional Coordinate Systems

# Three-Dimensional Coordinate Systems

Just as you can put Cartesian (or rectangular) coordinates on the plane using an  $x$ -axis and a  $y$ -axis which are perpendicular, you can also put **Cartesian** (or **rectangular**) **coordinates** on 3-dimensional space. Here, you use an  $x$ -axis, a  $y$ -axis, and a  $z$ -axis.

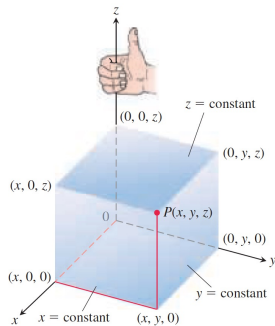
The  $y$ -axis goes left and right. The  $z$ -axis goes up and down. The  $x$ -axis goes forward and backward out of the plane of the drawing. Because of this, the  $x$ -axis is drawn at an angle to provide perspective.

The axes are labeled so that the coordinate system is a **right hand coordinate system**.

See the sketch on the next slide.

# Three-Dimensional Coordinate Systems

Figure: Three-Dimensional Coordinates



**FIGURE 12.1** The Cartesian coordinate system is right-handed.

# Three-Dimensional Coordinate Systems

The coordinate system consists of three **coordinate planes**.

The set of points  $x = 0$  is the **yz-coordinate plane**. It is the plane of the paper.

The set of points  $y = 0$  is the **xz-coordinate plane**. It is a vertical plane coming out toward you from the plane of the paper.

The set of points  $z = 0$  is the **xy-coordinate plane**. It is a horizontal plane coming out toward you from the plane of the paper.

# Three-Dimensional Coordinate Systems

The coordinate planes divide space into eight **octants**. Only one octant is named. The **first octant** is the set of all points in space where  $x > 0$ ,  $y > 0$ , and  $z > 0$ . It is the octant you are looking at when you draw the axes as in the preceding picture.

# Three-Dimensional Coordinate Systems

A point in space is given by an ordered triple of numbers  $(a, b, c)$ .

You go  $a$  units in the  $x$  direction. If  $a > 0$ , that is coming out toward you. If  $a < 0$ , that is going backward away from you.

You go  $b$  units in the  $y$  direction. If  $b > 0$ , that is going to the right. If  $b < 0$ , that is going to the left.

You go  $c$  units in the  $z$  direction. If  $c > 0$ , that is going up. If  $c < 0$ , is going down.

# Linear Equations in Three Variables

# Linear Equations in Three Variables

A plane in space is given by one nonzero linear equation,  $ax + by + cz = d$ , where at least one of  $a$ ,  $b$ , and  $c$  is not zero.

A line in space is given by two nonzero linear equations:

$$\begin{cases} a_1x + b_1y + c_1z = d_1 \\ a_2x + b_2y + c_2z = d_2 \end{cases}$$

This is simply the line where the two planes given by these two equations intersect.

# Linear Equations in Three Variables

It is possible that two linear equations define the same plane. In this case, the planes are **coincident**. This happens when  $(a_1, b_1, c_1, d_1)$  is a constant multiple of  $(a_2, b_2, c_2, d_2)$ .

It is possible that two linear equations define planes that do not meet. In this case, the planes are **parallel**. This happens when  $(a_1, b_1, c_1)$  is a constant multiple of  $(a_2, b_2, c_2)$ , but  $(a_1, b_1, c_1, d_1)$  is not a constant multiple of  $(a_2, b_2, c_2, d_2)$ .

# Regions in Space

# Regions in Space

A region given by  $ax + by + cz \geq d$  or  $ax + by + cz \leq d$  (once again with at least one of  $a$ ,  $b$ , and  $c$  is not zero) is a **closed half-space**.

A region given by  $ax + by + cz > d$  or  $ax + by + cz < d$  (once again with at least one of  $a$ ,  $b$ , and  $c$  is not zero) is an **open half-space**.

Other regions can also be defined by equalities and inequalities.

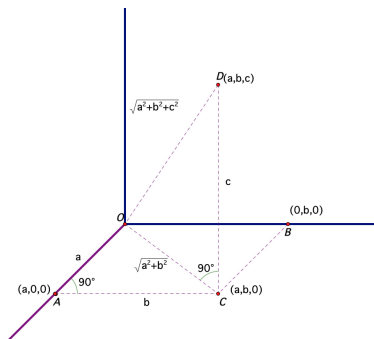
# Distance and Spheres in Space

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The distance between two points  $P_1(x_1, y_1, z_1)$  and  $P_2(x_2, y_2, z_2)$  is

$$|P_1P_2| = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2}.$$

This formula is gotten by applying the Pythagorean Theorem twice to two perpendicular right triangles.



# Distance and Spheres in Space

The standard form of the equation of a sphere with center  $(a, b, c)$  and radius  $r > 0$  is

$$(x - a)^2 + (y - b)^2 + (z - c)^2 = r^2.$$

This says the distance from the point  $(x, y, z)$  to the point  $(a, b, c)$  is  $r$ .

## Example

# Example

## Example

Find the center  $C$  and radius  $r$  for the sphere

$$2x^2 + 2y^2 + 2z^2 + x + y + z = 9$$

# Example

## Solution

What you have to do here is to complete the square in each of  $x$ ,  $y$ , and  $z$ .

$$2x^2 + 2y^2 + 2z^2 + x + y + z = 9$$

$$x^2 + y^2 + z^2 + \frac{1}{2}x + \frac{1}{2}y + \frac{1}{2}z = \frac{9}{2}$$

$$\left(x^2 + \frac{1}{2}x + \right) + \left(y^2 + \frac{1}{2}y + \right) + \left(z^2 + \frac{1}{2}z + \right) = \frac{9}{2}$$

# Example

## Solution (cont.)

$$\begin{aligned} \left(x^2 + \frac{1}{2}x + \frac{1}{4}\right) + \left(y^2 + \frac{1}{2}y + \frac{1}{4}\right) + \left(z^2 + \frac{1}{2}z + \frac{1}{4}\right) &= \frac{9}{2} \\ \left(x^2 + \frac{1}{2}x + \left(\frac{1}{4}\right)^2\right) + \left(y^2 + \frac{1}{2}y + \left(\frac{1}{4}\right)^2\right) & \\ + \left(z^2 + \frac{1}{2}z + \left(\frac{1}{4}\right)^2\right) &= \frac{9}{2} + \frac{1}{16} + \frac{1}{16} + \frac{1}{16} \\ \left(x + \frac{1}{4}\right)^2 + \left(y + \frac{1}{4}\right)^2 + \left(z + \frac{1}{4}\right)^2 &= \frac{75}{16} \\ \left(x + \frac{1}{4}\right)^2 + \left(y + \frac{1}{4}\right)^2 + \left(z + \frac{1}{4}\right)^2 &= \left(\frac{5\sqrt{3}}{4}\right)^2. \end{aligned}$$

# Example

## Solution (cont.)

From the equation

$$\left(x + \frac{1}{4}\right)^2 + \left(y + \frac{1}{4}\right)^2 + \left(z + \frac{1}{4}\right)^2 = \left(\frac{5\sqrt{3}}{4}\right)^2,$$

we see that this is an equation of the sphere with radius  $\frac{5\sqrt{3}}{4}$  and center  $\left(-\frac{1}{4}, -\frac{1}{4}, -\frac{1}{4}\right)$ .

# Working with Vectors in $\mathbb{R}^3$

# Vector Representations

Just like two-dimensional vectors, three-dimensional vectors are quantities with both magnitude and direction, and they are represented by directed line segments (arrows). With a three-dimensional vector, we use a three-dimensional arrow. Three-dimensional vectors can also be represented in component form.

# Vector Representations

The notation  $\mathbf{v} = \langle x, y, z \rangle$  is a natural extension of the two-dimensional case, representing a vector with the initial point at the origin,  $(0, 0, 0)$ , and terminal point  $(x, y, z)$ . The zero vector is  $\mathbf{0} = \langle 0, 0, 0 \rangle$ . So, for example, the three dimensional vector  $\mathbf{v} = \langle 2, 4, 1 \rangle$  is represented by a directed line segment from point  $(0, 0, 0)$  to point  $(2, 4, 1)$ .

# Vector Representations

Just as in the plane, vectors can be given by the initial point and terminal point.

Let  $\mathbf{v}$  be a vector with initial point  $(x_i, y_i, z_i)$  and terminal point  $(x_t, y_t, z_t)$ . Then we can express  $\mathbf{v}$  in component form as

$$\mathbf{v} = \langle x_t - x_i, y_t - y_i, z_t - z_i \rangle.$$

# Vector Operations

# Vector Operations

## Definition

Let  $\mathbf{v} = \langle x_1, y_1, z_1 \rangle$  and  $\mathbf{w} = \langle x_2, y_2, z_2 \rangle$ , and let  $k$  be a scalar.

**Scalar multiplication:**  $k\mathbf{v} = \langle kx_1, ky_1, kz_1 \rangle$

**Vector addition:**

$$\begin{aligned}\mathbf{v} + \mathbf{w} &= \langle x_1, y_1, z_1 \rangle + \langle x_2, y_2, z_2 \rangle \\ &= \langle x_1 + x_2, y_1 + y_2, z_1 + z_2 \rangle\end{aligned}$$

**Vector subtraction:**

$$\begin{aligned}\mathbf{v} - \mathbf{w} &= \langle x_1, y_1, z_1 \rangle - \langle x_2, y_2, z_2 \rangle \\ &= \langle x_1 - x_2, y_1 - y_2, z_1 - z_2 \rangle\end{aligned}$$

# Vector Operations

## Definition

Let  $\mathbf{v} = \langle x_1, y_1, z_1 \rangle$  and  $\mathbf{w} = \langle x_2, y_2, z_2 \rangle$ , and let  $k$  be a scalar.

**Vector magnitude:**  $\|\mathbf{v}\| = \sqrt{x_1^2 + y_1^2 + z_1^2}$

**Unit vector in the direction of  $\mathbf{v}$ :**

$$\frac{1}{\|\mathbf{v}\|} \mathbf{v} = \frac{1}{\|\mathbf{v}\|} \langle x_1, y_1, z_1 \rangle = \left\langle \frac{x_1}{\|\mathbf{v}\|}, \frac{y_1}{\|\mathbf{v}\|}, \frac{z_1}{\|\mathbf{v}\|} \right\rangle$$

if  $\mathbf{v} \neq \mathbf{0}$ .